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Homer Reids Solutions to Goldstein Problems: Chapter 8. Problem 8.6 A Hamiltonian of one degree of freedom has the form H= ba kq 2 p2 bqpet + q 2 et (+ bet) +, 2a 2 2. where a, b, , and k are constants. Note: I think there must be a misprint in the book; the coefficient of p2 in the first term is printed there as 1/2, which doesnt make sense dimensionally in light of the rest of the terms in ...

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4 Goldstein 8.26 4.1 Part (a) In the given con guration, both springs elongate or compress by the same magnitude. Suppose qdenotes the position of the mass mfrom the left end. At t= 0, q(0) = a=2, but the unstretched lengths of both springs are given to be zero. Therefore, the elongation (compression) of spring k 1 is qand the compression (elongation) of spring k 2 is q. The potential energy ...

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differential equation for the kinetic energy: dT dt = F·v while if the mass varies with time the corresponding equation is d(mT) dt = F·p. Answer: dT dt = d(1 2 mv 2) dt = mv·v・ = ma·v = F·v with time variable mass, d ...

Goldstein Chapter 1 Derivations - Michael R.R. Good
The constraint that the mass is on the wedge is r = R + l(cos α, sin α), or x = X + l cos α and y = l sin α 8 where l is the distance the mss traveled down the wedge. This is one constraint, which we can express as a function of x, y, X as f = (x − X) sin α − y cos α = 0.